



Profile ADIRO Automatisierungstechnik

Consulting, planning and implementation of automation projects for industry, trade and educational institutions

Our core competencies - holistic problem solutions:

- A Robotics in assembly, production and quality control
- A Laboratory automation
- PLC controls and networking
- Operation, monitoring, visualization
- Optimization of plants and work processes
- Training, workshops, coaching
- A Documentation





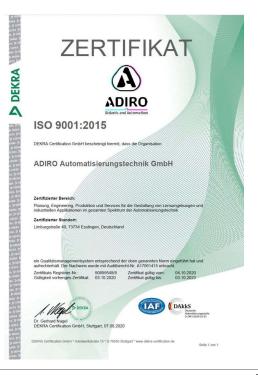
Profile ADIRO Automatisierungstechnik

Since our establishment in 1990, numerous national and international customers placed their trust in Adiro.

In the robotics sector, we are a certified member of the Automation network of Mitsubishi Electric.



We see our ISO 9001 certification as an obligation for continuous improvements for the benefit of our customers!





Profile ADIRO Automatisierungstechnik

In April 2020 ADIRO Automatisierungstechnik GmbH celebrated their 30th anniversary.

3 decades of innovative solutions in the broad spectrum of automation technology.





Prize winners of the competition:

100 locations for Industry 4.0 in Baden-WürttembergAward for the development and implementation of an

exemplary Industry 4.0 solution





Robotics system partner of Mitsubishi Electric

We have been a certified system partner for integration since May 2003 of Mitsubishi robot

systems.

Based on decades of experience, we offer specialist knowledge in the following areas:

- Customized Training
- A Feasibility studies, proof of process
- Integrations
- A Programing
- Documentation
- Services / optimizations





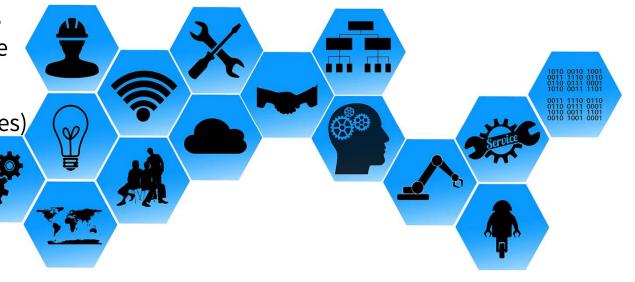
Robot programing requirements

Process security, monitoring and communication

Processes that are becoming more complex with increasing demands on the software require a consistent communication structure. (Industry 4.0, AI, digital twin)

Modern bus and communication systems for data transfer from the robot cell to the office world.

Intelligent HMI (human-machine interfaces) are becoming more and more important to relieve the plant operator.



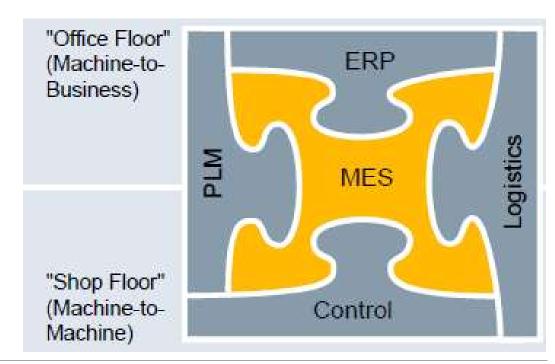
Quelle: www.pixabay.com



Robot programming requirements

In addition to the sequence programming, further aspects must be taken into account:

- Create logistics and material flow concepts
- Adaptation to various software standards
- Integration of various automation components, PLC, vision systems, Lasers, CNC machines ...
- Establish system operation with the worker
- Consider safety aspects (MRL standard)
- Error behavior, -evaluation and -robustness
- Process modularity
- Amortization considerations, number of items, cycle times, variety of types, set-up time minimization ...
- Integration of IT world / IT security





Application programming Robotic

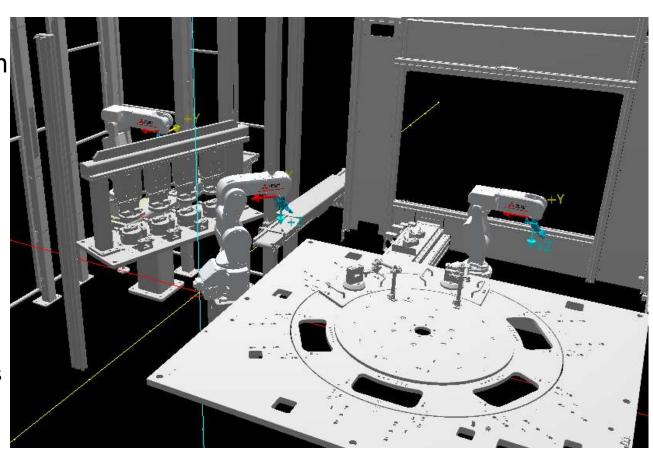
- Complete control of systems, including visualization (HMI) and remote maintenance
- Camera-guided robot applications
- Control of additional axes
- A Conveyor Tracking
- Automation solutions for CNC machines
- Operator interfaces (HMI)
- Real-time applications
- A 3D Bin Picking (grap in the box)





Feasibility studies, simulation, cycle time analysis and optimization

- Preliminary tests for automation processes and -ideas with our demonstration robots in Adiro or at customers site.
- Cycle time analysis and optimization in the construction phase with RT Toolbox 2/3. (Virtual robot)
- Cycle time analysis and optimization on the real system
- A Creation and elaboration of control concepts for entire systems





Programming templates

- Development of customer-specific programming standards (templates) and interfaces
- Support and process support in the implementation of the templates for customer projects

```
1480
1481
       ' Application main entry point
1482
1483
       *Main
1484
        DOTaskRequest=1
                                       ' Set ready for task
1485
         Wait DIStrobe=1
                                      ' Wait for a new task
                                       ' Reset ready for task
1486
        DOTaskRequest=0
                                      ' Read task data from PLC
1487
         iTask%=DITask
1488
         DOTask=iTask%
                                       ' Mirror task data back to PLC
                                      ' Set 'task has been read' to PLC
1489
        DOTaskRead=1
1490
         Wait DIStrobe=0
                                      ' Wait for reset PLC signal
1491
        DOTaskRead=0
                                       ' Reset 'task has been read' to PLC
1492
         If(iNeedToHome%=1 And iTask%<>1) Then Error 9105' Task selection not allowed -
        If(iTask%=1) Then GoTo *Homing
                                                ' <Tasks Number="1" Label="*Homing" Descrip</p>
1493
1494
        If(iTask%=2) Then GoTo *Service
                                               ' <Tasks Number="2" Label="*Service" Descrip</p>
        If(iTask%=3) Then GoTo *DropPart
                                               ' <Tasks Number="3" Label="*DropPart" Descr</p>
1495
        If(iTask%=4) Then GoTo *Spare
                                               ' <Tasks Number="4" Label="*Spare" Description</p>
1496
        If(iTask%=5) Then GoTo *PickFromConv ' <Tasks Number="5" Label="*PickFromConv
1497
                                                ' <Tasks Number="6" Label="*PlaceToRT" De</p>
1498
        If(iTask%=6) Then GoTo *PlaceToRT
1499
        If(iTask%=7) Then GoTo *PickFromDrawer ' <Tasks Number="7" Label="*PickFromDraw
1500
         Error 9103
                                   ' Error: unknown task selection
       GoTo *Main
                                     ' Get back to main loop
1501
1502
1503
1504
       ' Homing Procedure
1505
```

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Life Science

As a flexible and innovative company, we can implement your requirements in a targeted manner thanks to our expertise in life sciences and automation technology

Development and construction of laboratory equipment according to customer-specific requirements



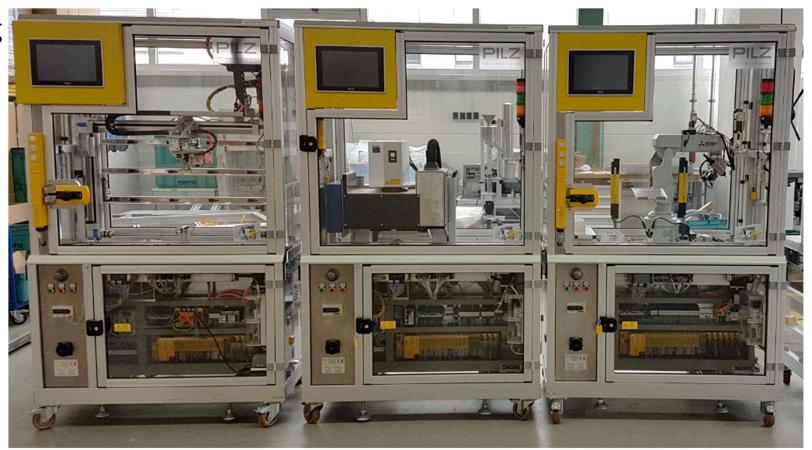


Left picture: Ion exchanger



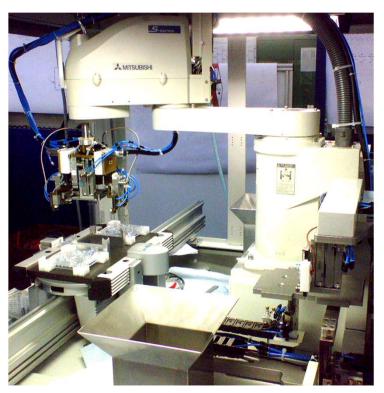
Mechanics engineering

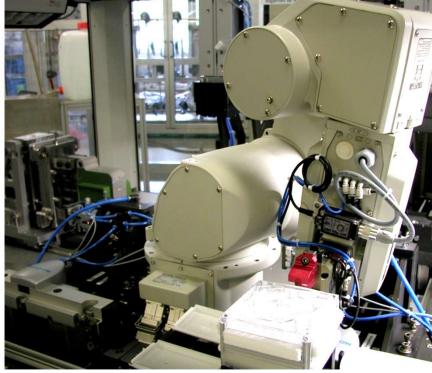
- 3D construction (Creo)
- Electrical construction (E-Plan) Montage
- Orbital welding





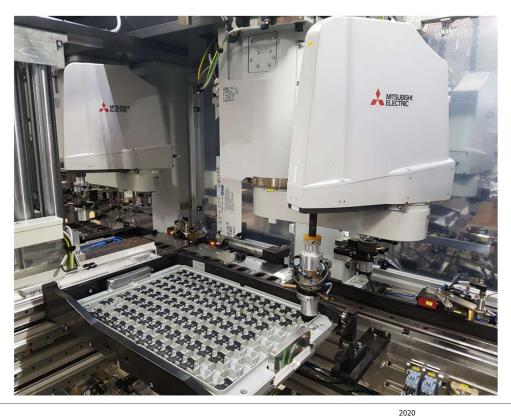
Medical, Pharma







Automotive







Electronics

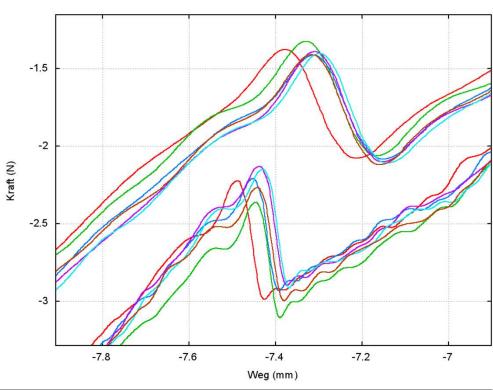




Haptic

RoHaC[®] developed in collaboration with CMO-SYS GmbH





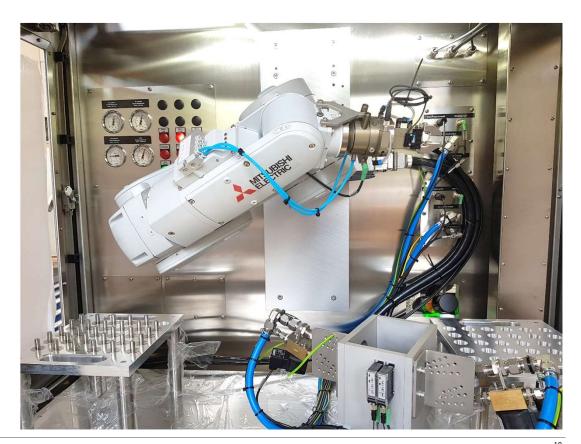


Packaging





Clean room





HRC (human robot collaboration)







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Support

Robotic

- A Software-Support
- A Remote-Support
- Android Apps (Melfa client, Melfa Error)
- Documentation
- CE marking

Assembly













Tools

Robotic (Mitsubishi)

- A RT ToolBox2 / RT ToolBox3
- A Ciros Studio
- ADIRO Apps (Melfa Client, Melfa Error)
- A E-Designer
- **ADIRO Robot Studio** (Planning tool and for the automated creation of program code)

```
content: ";
                                                   blockquote p [ margin-bottom: 10px ]
   content: none;
                                                    strong, b [ font-weight: bold ]
                                                    em, i, cite (
table [
                                                      font-style: normal;
   border-collapse; collapse;
                                                      font-family: arial;
   border-spacing: 0:
                                                    small [ font-size: 100% ]
button, input, select, textarea [ margin: 0 ]
                                                    figure [ margin: 10px 0 ]
focus [ outline: 0 ]
                                                    code, pre l
a:link { -webkit-tap-highlight-color: #FF5E99 }
                                                      font-family: monospace,consolas,sans-serif;
img, video, object, embed (
                                                      font-weight: normal;
   max-width: 100%:
                                                      font-style: normal;
   height: auto!important;
iframe [ max-width: 100% ]
                                                       margin: 5px 0 20px 0:
blockquote (
                                                      line-height: 1.3em:
   font-style: italic;
                                                      padding: 8px 10px;
   font-weight: normal:
                                                      overflow: auto:
   font-family: Georgia, Serif;
   font-size: 15px;
   padding: 0 10px 20px 27px;
                                                             ng: 0 8px;
   position: relative:
                                                             pight: 1.5:
   margin-top: 25px;
blockquote:after [
                                                                1px 6px.
   position: absolute;
                                                               0.2px;
   content: ""
                                                              daek
```



Training

Robot training (German / English)

- Lecturers for robotics (didactically and methodically trained)
- A Partner for inter-company robot training
- Modular standard training program for professional teaching of the basics and expert knowledge in robotics
- In-house seminars for customers with training robots and / or with the real machine
- Seminar content specially oriented to customer demands





Project support, Coaching

Training on the Job, together with your employees (German / English)

- Setup of robots
- Elaboration of a program structure with the aim of developing a binding programming template
- Programming and commissioning of the robots
- Support through all project phases up to the acceptance of the machine
- A Documentation
- Interim project management robotics





Consulting robot automation

Introduction and expansion of robot technology (German / English)

- A Inventory of the current situation
- Determination of automation potential
- A Optimization of existing processes
- A Further development and feasibility studies
- Consulting and selection of the required robot system
- A Project support





Manufacturer portfolio

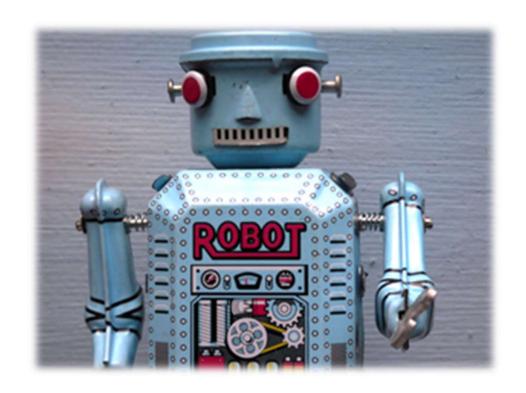
Robotic Skills

- Mitsubishi (First Choice)
- ABB
- Yaskawa
- A KUKA
- Fanuc
- A Festo Robotino®





Questions?



Thank you for your attention!

Stephan Kühne

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